

ROS Community Metrics

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Reporting on August 2013

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Source: Metrics categories borrowed from Dawn Foster of MeeGo:
<http://wiki.meego.com/Metrics>

Awareness Metrics

Discovering the community, learning more about it
(potential community members)

ros.org: Visitors & Page Views

[Email](#) [Export](#) ▾ [Add to Dashboard](#) [Shortcuts](#)All Visits
100.00%

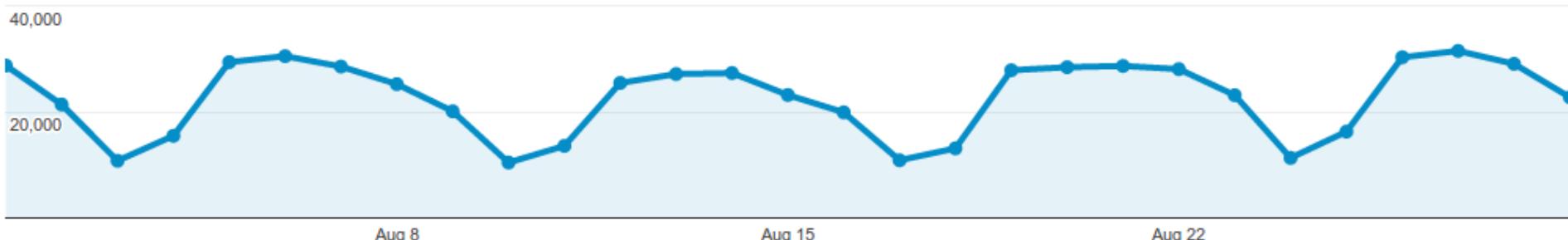
Overview

Site: ros.org/wiki
Source: Google Analytics

Pageviews ▾ VS. Select a metric

Hourly Day Week Month

● Pageviews

**Pages on this site were viewed a total of 658,460 times**

Site Content

Page

Page Title

Site Search

Search Term

Events

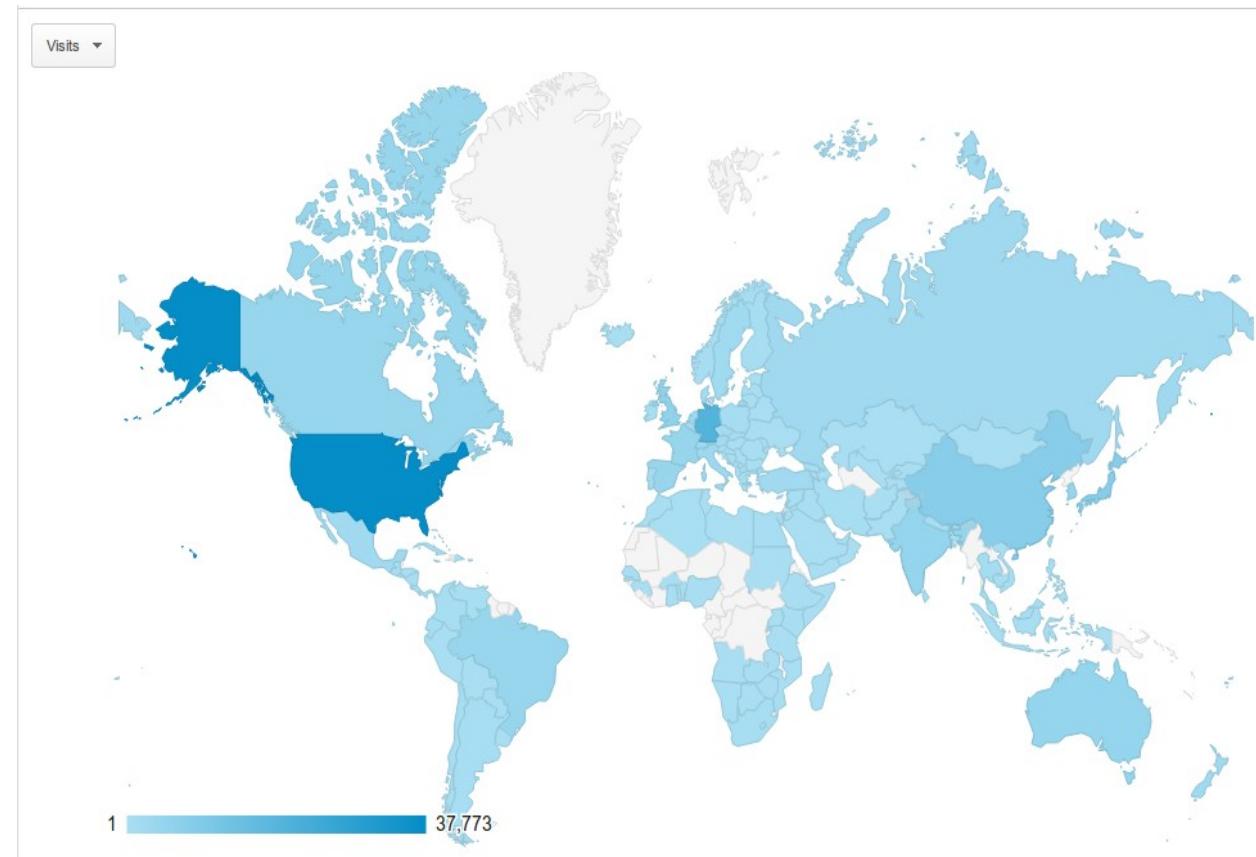
Event Category

Page

	Page	Pageviews	% Pageviews
1.	/wiki/	55,690	8.46%
2.	/wiki/ROS/Tutorials	34,593	5.25%
3.	/wiki/ROS/Installation	21,209	3.22%
4.	/wiki/groovy/Installation/Ubuntu	12,720	1.93%
5.	/wiki/ROS/Tutorials/InstallingandConfiguringROSEnvironment	9,084	1.38%
6.	/wiki/Robots	5,786	0.88%
7.	/wiki/ROS/Tutorials/CreatingPackage	5,702	0.87%
8.	/wiki/ROS/Tutorials/WritingPublisherSubscriber(c++)	5,578	0.85%
9.	/wiki/catkin/Tutorials/create_a_workspace	5,560	0.84%
10.	/wiki/ROS/Tutorials/NavigatingTheFilesystem	5,357	0.81%

ros.org visitor locations:

1. United States	37,773
2. Germany	19,666
3. China	7,822
4. Japan	7,714
5. United Kingdom	5,672
6. India	4,745
7. Australia	4,734
8. Canada	4,145
9. Brazil	4,122
10. France	4,074
11. South Korea	4,050
12. Spain	3,951
13. Italy	2,849
14. Singapore	2,612
15. Russia	2,162
16. Mexico	2,097
17. New Zealand	2,073
18. Sweden	2,040
19. Turkey	1,849
20. Switzerland	1,795



Source: Google Analytics
Site: ros.org/wiki in August

Public ros.org Mirrors

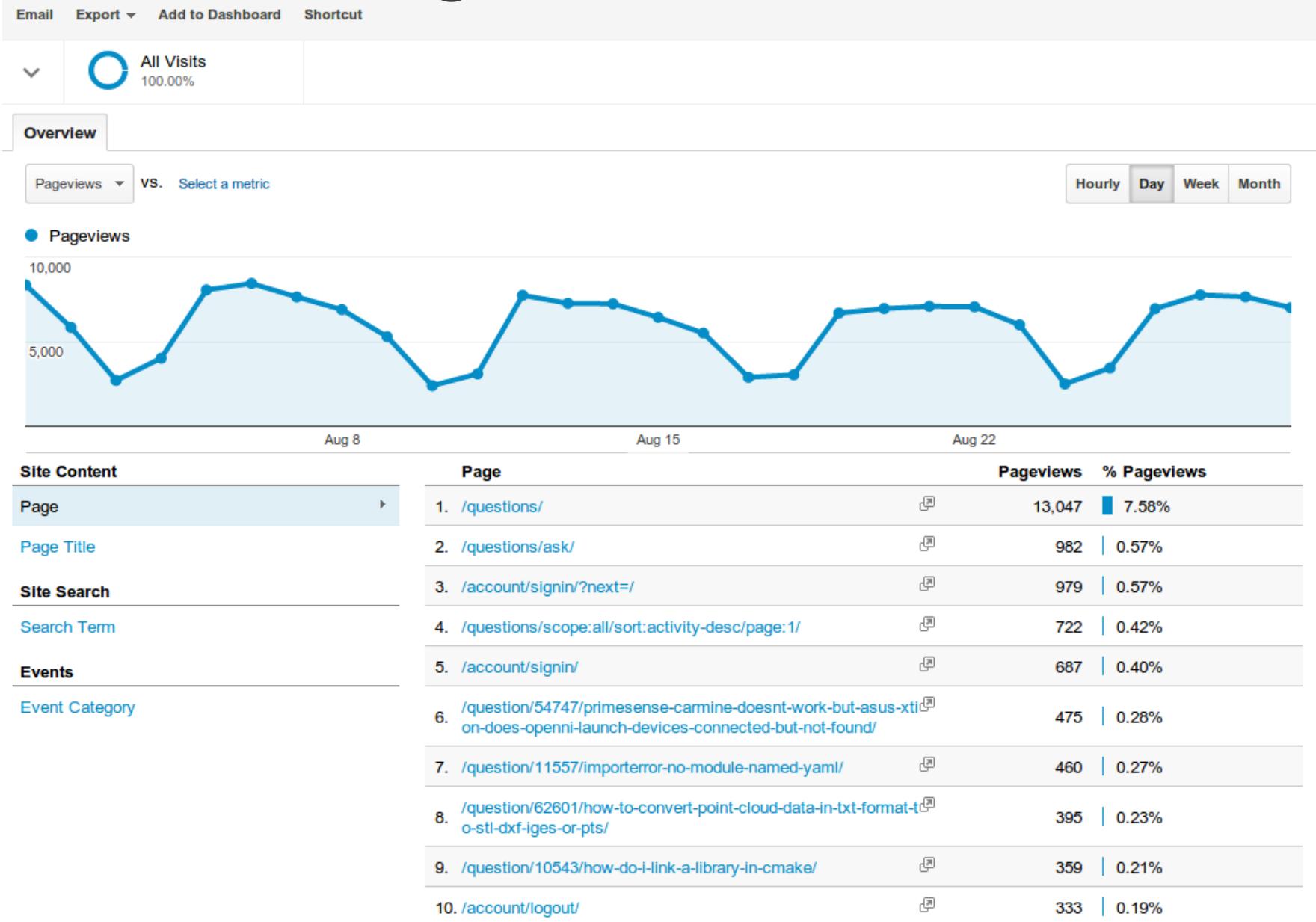
- Asia:
 - Tokyo, Japan
 - Europe:
 - Freiburg, Germany
 - Lisbon, Portugal
 - Barcelona, Catalonia
 - Porto, Portugal
 - North America:
 - College Park, Maryland
 - Philadelphia, Pennsylvania (www.pennros.org)
 - Austin, Texas
- Data not included from these sources
<http://www.ros.org/wiki/Mirrors>

`answers.ros.org:`
visitors

answers.ros.org visitors: August 2013

Overview

Aug 1, 2013 - Aug 29, 2013



Membership Metrics

Taking the time to sign up and join the community
(passive and active community members)

Site & list membership

- Ros-users mailing list subscribers:
 - 1570
- ros.org wiki users:
 - 3359
- answers.ros.org users:
 - 5757

Engagement Metrics

Interacting with other community members
(active community members)

ros.org: activity

- Wiki pages:
 - 22,626
- Wiki page edits:
 - 31.4 / day (averaged over August)
- Wiki page views:
 - 22,705.5 / day (averaged over August)

Source: MoinMoin, Google Analytics (sampled 2013-09-20)

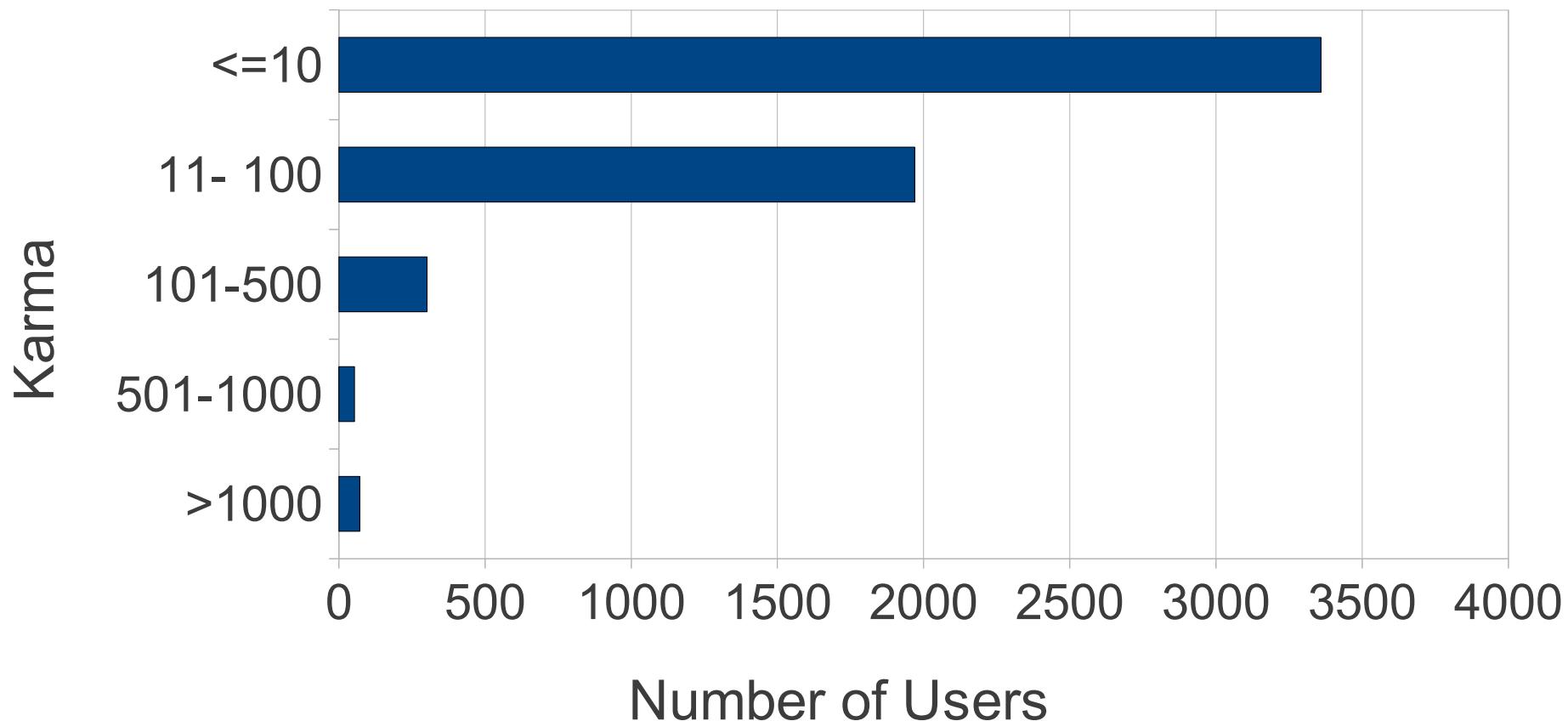
answers.ros.org: activity

- Total questions:
 - 13,095
- Unanswered questions:
 - 3,537 (27%)
- New questions in August:
 - 394 (12.7 / day)

Source: Askbot Sampled: 9/20/2013

answers.ros.org Karma

Sampled 2013-09-20



Users get karma points for having answers upvoted (+10) or accepted (+15) and for accepting someone else's answer (+2).
Histogram of users by karma

Code Metrics

Engaging with the ROS project at a code level
(developers and users)

Binary Downloads – August 2013

- Total Unique IP addresses downloading .deb files:
 - 11,078
- Total downloads of .deb packages:
 - 1,599,288
- Total number of packages downloaded as .deb files:
 - 2,593
- Number of unique .deb packages downloaded:
 - 32,591

Source: Apache2, filtered for public
repo, not testing repo(shadow-fixed)

Top 40 Downloaded Packages

Direct downloads from packages.ros.org - August 2013

python-rosPKG	10028	ros-groovy-rqt-common-plugins	6704
ros-groovy-image-proc	8388	ros-groovy-simulator-gazebo	6662
ros-groovy-depth-image-proc	8357	ros-groovy-rqt-image-view	6661
ros-groovy-image-view	8260	ros-groovy-navigation-tutorials	6567
ros-groovy-image-pipeline	8215	ros-groovy-visualization-tutorials	6539
ros-groovy-stereo-image-proc	8122	python-catkin-pkg	6503
ros-groovy-desktop-full	7693	ros-groovy-rqt-robot-plugins	6378
ros-groovy-nodelet	7013	ros-groovy-rqt-rviz	6298
ros-groovy-nodelet-topic-tools	6921	python-rosdistro	6271
ros-groovy-pcl-ros	6890	ros-groovy-camera-calibration	6152
ros-groovy-nodelet-core	6874	ros-groovy-image-rotate	5962
ros-groovy-navigation	6844	python-rosdep	5297
ros-groovy-perception-pcl	6813	ros-groovy-catkin	4877
ros-groovy-rviz	6792	ros-groovy-rosCPP	4846
ros-groovy-laser-filters	6771	ros-groovy-std-msgs	4828
ros-groovy-laser-assembler	6769	ros-groovy-roslib	4809
ros-groovy-rqt-gui-cpp	6749	ros-groovy-cpp-common	4807
ros-groovy-laser-pipeline	6737	ros-groovy-genmsg	4806
ros-groovy-common-tutorials	6729	ros-groovy-rosPack	4806
ros-groovy-slam-gmapping	6721	ros-groovy-rosCPP-serialization	4805

Public Debian Package Mirrors

- Freiburg (Germany)
- University of Maryland (USA)
- Case Western Reserve University (USA)

Statistics not counted from these sources

<http://wiki.ros.org/ROS/Installation/UbuntuMirrors>

rosdistro activity

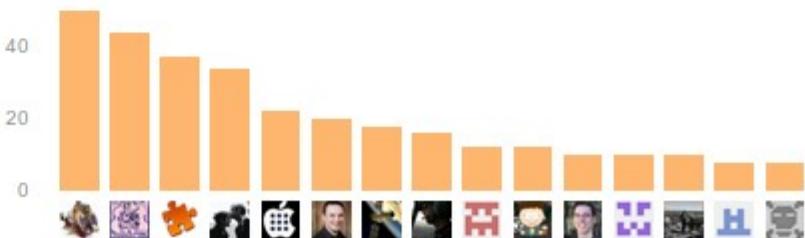
PUBLIC  ros / rosdistro Unwatch 20 Unstar 70 Fork 253

August 23 2013 - September 23 2013 Period: 1 month

Overview

	
336 active pull requests	10 active issues
 334 merged pull requests	 2 proposed pull requests
 10 closed issues	 0 new issues

41 authors have pushed **385 commits** to all branches, excluding merges. On master, **14 files** have changed and there have been **715 additions** and **199 deletions**.



 **334** Pull Requests merged by **37** people

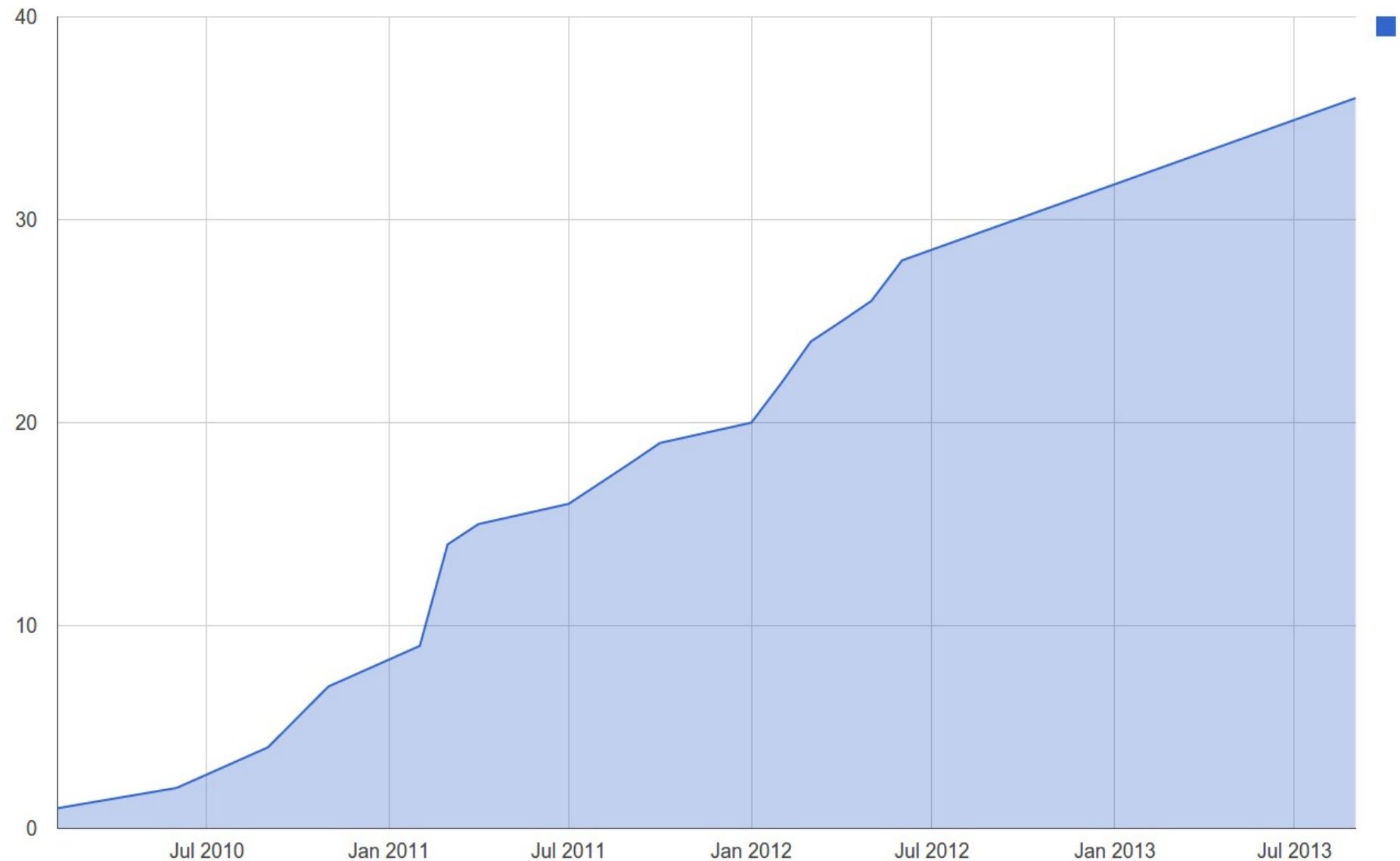
Research use

Number of papers citing “ROS: an open-source Robot Operating System” (Quigley et al., 2009):

748

Source: Google Scholar 2013-09-20

Robots officially supporting ROS



Source: Ken Conley, Tully Foote,
wiki.ros.org/Robots